Guided Proofreading of Automatic Segmentations for Connectomics

Supplemental Material

Daniel Haehn*1, Verena Kaynig1, James Tompkin2, Jeff W. Lichtman1, and Hanspeter Pfister1

¹Harvard University ²Brown University

	Traditional Network		Residual Network	
Conv. Layers	2	4	5	13
Dropout Reg.	у	у	у	n
Cost [m]	27.5	383	5080	1094
Test. Acc.	0.925	0.94	0.93	0.90
Prec./Recall	0.93/0.93	0.94/0.94	0.7/0.53	0.74/0.66
F1 Score	0.93	0.94	0.39	0.64
		*		

Table 1: Traditional CNN Architecture versus Residual Network Architecture [2]. All configurations are compared using the same parameters. Our final choice (indicated by *) trains relatively fast and performs better.

1. Classifier

1.1. Architecture

We explored different architectures for the convolutional neural network (CNN) for split error detection. We compare traditional CNN architectures versus residual networks [2] (Tab. 1). The traditional architecture with dropout regularization generalized better than residual networks on unseen testing data.

1.2. Training Parameters

We performed a limited brute force parameter search to tune the split error classifier (Tab. 2). This resulted in 3240 different CNN configurations which were evaluated on 10% of our training data. Learning rate and momentum ranges are defined linearly across 2000 epochs.

1.3. Automatic Method Threshold p_t

For automatic selection, we observed a threshold $p_t = 0.95$ as stable when evaluating on previously unseen testing data (Mouse S1 AC3 Open Connectome Project dataset).

Parameter	Search Space
Filter size:	3x3 , 5x5, 9x9, 13x13
No. Filters 1:	32, 48, 64
No. Filters 2-4:	32, 48 , 64
Dense units:	256, 512
Learning rate:	0.00001, 0.0001, 0.001, 0.01, 0.03-0.00001
Momentum:	0.9, 0.95, 0.9-0.999
Mini-Batchsize:	10, 100, 128

Table 2: Brute force parameter search for the split error classifier. The final parameters are highlighted.



Figure 1: Observations of probability thresholds p_t during automatic selection on three different subvolumes of previously unseen testing data. The dashed lines show when $p_t = 0.95$ is reached.

This means that automatic selection stops once all borders with $p_t \ge 0.95$ were proofread. Figure 1 shows split error classification on three randomly selected subvolumes ($700 \times 700 \times 2$ voxels) of AC3. In all cases, the threshold $p_t = 0.95$ reduces VI.

^{*}Corresponding author, haehn@seas.harvard.edu

1.4. Input channel contributions

All four input channels help to reduce VI (Table 3). As identified by Bogovich *et al.* [1], image data adds intracellular structures (e.g., vesicles) to the decision process, and membrane probabilities include global knowledge of the staining protocol to highlight cell membranes. Then, the label channel provides knowledge about neuron shapes while the dilated mask of the border covers the gap of extra-cellular space. Adding the dilated mask of the border decreases VI.

Input channels	VI reduction
Image + Prob.	-0.094
Prob. + Border	-0.080
Image + Prob. + Border	-0.045
Label + Border	-0.008
Image + Prob. + Label	0.038
Prob. + Label + Border	0.041
Image + Prob. + Label + Border	0.065

Table 3: Automatic selection on the AC4 subvolume with $p_t = 0.95$ using the guided proofreading classifier; median VI reduction in ascending order. The combination of all four input channels performs best.

1.5. Merge Error Detection Pseudo Code

We provide pseudo code on how we detect merge errors to foster understanding of the reported algorithm (Alg. 1). In our experiments, we use N = 50 iterations.

Alg	orithm 1 Merge Error Detection for a label <i>l</i>
1:	$l_d = \text{dilate}(l, 20)$
2:	invImage = invert(image)
3:	for N iterations do
4:	$s_1, s_2 = randomSeedsOnBoundary(l_d)$
5:	wsImage = watershed(invImage, l_d , s_1 , s_2)
6:	border = border (wsImage)
7:	p = rank(border)
8:	$p_{\text{merge}} = 1 - p$
9:	find (max p_{merge})

1.6. Limitations

Guided proofreading works on 2D image sections. This enables error correction without a computationally expensive alignment process. However, the output requires an additional (block-)merging step prior to 3D analysis. Several software packages exist for this purpose.

As described in Section 5, the guided proofreading classifier has to be retrained if used on a different species than mouse. In our experiments, parameters did not need to be changed.



Figure 2: The five different datasets we use for evaluation. The top row shows the first slice of the AC4 and L. Cylinder mouse brain datasets as reported in the paper. The bottom row shows the first slice of the CREMI A/B/C fruit fly datasets which we used for additional experiments.

2. Automatic Segmentation Pipeline

We create a dense automatic segmentation of electron microscopy data using a combination of a U-net [6] and the GALA agglomeration method [4]. To not bias, these classifiers are trained on different data than GP (Tab. 4).

Training Set	Training Set	Test Set
U-Net / GALA	GP	GP
AC3+AC4	L. Cylinder	L. Cylinder _{test}
$(1024 \times 1024 \times 175 \text{vx})$	$(2048 \times 2048 \times 250 \text{vx})$	$(2048 \times 2048 \times 50 \text{vx})$
AC4 excl. test	L. Cylinder	AC4 _{test} subvolume
$(1024 \times 1024 \times 90 \text{vx})$	$(2048 \times 2048 \times 250 \text{vx})$	$(400 \times 400 \times 10 \text{vx})$
AC3+AC4	CREMI A/B/C	CREMI A/B/Ctest
$(1024 \times 1024 \times 175 \text{vx})$	$(1250 \times 1250 \times 300 \text{vx})$	$(1250 \times 1250 \times 15 \text{vx})$

Table 4: Training data of membrane detection (U-Net / GALA) vs. training data of GP vs. test data.

GALA uses a random forest classifier to agglomerate segments. We use an agglomeration level of 0.3 (after a grid search). We follow the method by Knowles-Barley *et al.* as described in [3].

3. L. Cylinder Results

We report experiments and results on the L. Cylinder dataset in the paper. Figure 3 and 4 visualize the reported results measured as variation of information (VI). We compare automatic selection with threshold and selection oracle using focused proofreading and guided proofreading.

Best possible VI. The selection oracle using guided proofreading does not reach the best possible VI score. We cal-



Figure 3: Performance comparison of Plaza's focused proofreading and our guided proofreading on the L. Cylinder dataset as reported in the paper. All measurements are shown as median VI, the lower the better. We compare automatic selection with threshold ($p_t = 0.95$, green line) and the selection oracle for accepting or rejecting corrections using each method. Guided proofreading yields better results faster with fewer corrections.



Figure 4: VI distributions of guided proofreading (GP) and focused proofreading (FP) output across slices of the L. Cylinder dataset, with different error correction approaches. The variation resulting from performance of FP with automatic selection is $7.8 \times$ higher than GP (\uparrow), with median VI of 2.75 and SD = 0.789.

culate this score by intersecting the initial segmentation and the ground truth. In theory, the classifier should be able to reach this lower bound. However, due to the classification patch size, the membrane probability maps we used included a 30 pixel frame region. Guided proofreading ignores all segments within this frame region, and so cannot reach the best possible VI in some datasets.

4. Confirmatory Data Analysis

We use a single factor between-subject design with the factor being the proofreading method (GP, FP, or Dojo). Our hypothesis is that VI reduction is significantly better with GP than with other tools. For this, we treat VI as a continuous variable and use analysis of variance (ANOVA [7]) followed by parametric tests (Welch's t-test [8]).

AC4 subvolume. For novice performance, we observe a significant effect ($\alpha = 0.05$) of which proofreading tool is used for the three conditions GP, FP, and Dojo [F(2,27) = 6.446, p = 0.005] when comparing the mean VI outcome. Post hoc comparisons (after Bonferroni correction) indicate that the mean VI for GP is significantly lower than for FP [$t_{27} = -2.7696, p = 0.0168$], and that the mean VI for GP is significantly lower than for Dojo $[t_{27} = -4.407, p < 0.001]$. This means that novices using GP perform significantly better than using FP and Dojo. A similar trend is visible when comparing the expert performance between GP and FP as the change in mean VI of GP is significantly better ([F(1, 18) = 7.054, p = 0.016]and $[t_{18} = -2.6559, p = 0.0216]$). For automatic selection with threshold, the difference in mean VI is very large and GP also performs significantly better ([F(1, 18) =89.902, p < 0.001 and $[t_{18} = 9.482, p < 0.001]$). The final VI scores of the selection oracle with GP and FP are very similar and the difference between them is not significant [F(1, 18) = 0.795, p = 0.384]. However, the VI reduction rate of GP is much higher (Fig. 6, main paper, right).

L. Cylinder. The automatic selection with threshold yields similar results as on the AC4 dataset, and we observe a significant improvement when using GP instead of FP ([F(1,98) = 26.676, p < 0.001], post hoc comparison $[t_{98} = 5.1648, p < 0.001]$). The selection oracles of GP and FP result in very similar final VI scores and the difference is not significant [F(1,98) = 0.071, p = 0.790], but GP reaches minimum VI faster in 10,000 corrections versus FP in 26, 170 corrections.

5. Additional Experiments

CREMI A/B/C. As part of the MICCAI 2016 challenge on circuit reconstruction from electron microscopy images (CREMI), six ssTEM datasets were made publicly available¹, each $1250 \times 1250 \times 125$ voxels. Since only three datasets include manually-labeled 'ground truth', we use these three volumes for our experiments. The volumes are part of an adult fruit fly (Drosophila melanogaster) brain. The resolution of all three datasets is $4 \times 4 \times 40$ nm³/voxel. We evaluate error detection and correction on subvolumes of CREMI A/B/C with the dimensions $1250 \times 1250 \times 5$

http://www.cremi.org



Figure 5: Receiver Operating Characteristic curves comparing focused proofreading and guided proofreading automatic correction on the CREMI A/B/C fruit fly subvolumes. Guided proofreading performs better on all three datasets.

voxels. The subvolumes were cut from the last 25 sections of each of the three datasets and unseen during training. We compare focused proofreading and guided proofreading with automatic selection ($p_t = 0.95$) and selection oracle.

Retraining. Since the CREMI data is a different species, we simply retrain our split error classifier as well as focused proofreading by Plaza [5]. For this, we use the first 100 sections of each of the three CREMI datasets combined as training data. All parameters are unchanged and left as reported in the paper.

Classification Performance. Figure 5 compares the focused proofreading and guided proofreading classifiers on the CREMI A/B/C datasets. Our method exhibits higher sensitivity and lower fall-out.

5.1. CREMI A

Figure 6 and 7 compare Plaza's focused proofreading and guided proofreading on the five sections of CREMI A.

Selection oracle. With focused proofreading, the selection oracle reduces median VI to 0.928, SD = 0.043 from an initial median VI of 1.06 (SD = 0.055). 532 corrections out of 3707 were accepted. Guided proofreading does not reach the best possible VI, however, reduces VI faster with less corrections to 0.941 (SD = 0.04). Out of 4463 corrections, 1275 were accepted.



Figure 6: Performance comparison of Plaza's focused proofreading and our guided proofreading on 5 sections of the CREMI A dataset. All measurements are reported as median VI, the lower the better. The threshold for automatic selection is $p_t = 0.95$ (green line). The slope of the selection oracle shows that guided proofreading reduces VI faster.



Figure 7: VI distributions of guided proofreading (GP) and focused proofreading (FP) output across slices of the CREMI A dataset, with different error correction approaches. The variation resulting from performance of FP with automatic selection is $5.4 \times$ higher than GP (\uparrow), with median VI of 5.32 and SD = 0.009. GP does not reach the best possible VI as discussed in the text.

Automatic selection with threshold. Not surprisingly, focused proofreading performs poorly when ran automatically (VI of 5.32, SD = 0.009). Guided proofreading is able to reduce VI to 0.989 (SD = 0.043) with $p_t = 0.95$.

5.2. CREMI B

Figure 8 and 9 show the results on the CREMI B dataset.

Selection oracle. Focused proofreading is able to reduce median VI to 1.29, SD = 0.031 from an initial median VI of 1.63 (SD = 0.025). Out of 1959 corrections, the selection oracle accepted 517. With guided proofreading, the median VI is reduced to 1.30, SD = 0.03 while accepting 1111 corrections out of 3073.



Figure 8: Split error correction by Plaza's focused proofreading and our guided proofreading compared on the CREMI B dataset. All measurements are reported as median VI, the lower the better. Automatic selection with threshold (green line) yields reasonable performance using guided proofreading.



Figure 9: VI distributions of guided proofreading (GP) and focused proofreading (FP) output across 5 sections of the CREMI B dataset. We compare automatic selection and oracle selection. The variation resulting from performance of FP with automatic selection is $3 \times$ higher than GP (\uparrow), with median VI of 4.25 and SD = 0.07.

Automatic selection with threshold. Focused proofreading results in a VI of 4.25 (SD = 0.07). Guided proofreading reduces median VI to 1.43 (SD = 0.038).

5.3. CREMI C

The results of split error correction using focused proofreading and guided proofreading on the CREMI C subvolume are shown in Figure 10 and 11.

Selection oracle. With focused proofreading, the initial median VI of 1.75 (SD = 0.086) is reduced to 1.45 (SD =



Figure 10: Performance comparison of Plaza's focused proofreading and our guided proofreading on the CREMI C dataset. Lower VI scores are better. Guided proofreading corrects the initial segmentation faster with less corrections than focused proofreading. The green line shows the automatic threshold $p_t = 0.95$.



Figure 11: VI distributions of guided proofreading (GP) and focused proofreading (FP) output across the CREMI C subvolume, with different error correction approaches. The variation resulting from performance of FP with automatic selection is $3 \times$ higher than GP (\uparrow), with median VI of 4.81 and SD = 0.08.

0.056) with 670 accepted corrections out of 2694. Guided proofreading is able to reduce the VI to 1.47 (SD = 0.06). Here, the oracle accepted 1531 out of 4332 corrections.

Automatic selection with threshold. Focused proofreading results in a VI of 4.81 (SD = 0.03). Guided proofreading with $p_t = 0.95$ reduces median VI to 1.57 (SD = 0.081).



Figure 12: Participants were recruited with this flyer.

6. Forced Choice User Experiment

6.1. Recruitment and Participation

Novice participants were recruited via flyer (figure 12). An anonymized listing of all participants including demographic information is shown in table 5.

6.2. User Interface

We integrate guided proofreading into an existing large data connectomics workflow. The web-based system is designed with a novice-friendly user interface (Fig. 5 in the paper, and the supplemental video). We show the current labeling of a cell boundary outline and its proposed correction overlayed on EM image data. The user cannot distinguish the current labeling from the proposed correction to avoid selection bias. We also show a solid overlay of the current and the proposed labeling. In addition, we show the image without overlays to provide an unoccluded view. User interaction is simple and involves one mouse click on either the current labeling or the correction. After interaction, the next potential error is shown.

NASA Task Load Index

Hart and Staveland's NASA Task Load Index (TLX) method assesses work load on five 7-point scales. Increments of high, medium and low estimates for each point result in 21 gradations on the scales.

Name	Task		Date
Mental Demand	Hov	v mentally dem	nanding was the task?
Very Low			Very High
Physical Demand	How physica	lly demanding	was the task?
Very Low			Very High
Temporal Demand	How hurried	or rushed was	the pace of the task?
			Very High
Very LOW			very riign
Performance I	How succes you were asł	sful were you i ked to do?	n accomplishing what
Perfect			Failure
Effort	How hard die your level of	d you have to v performance?	work to accomplish
Very Low			Very High
Frustration I	How insecur and annoyed	e, discourageo I wereyou?	d, irritated, stressed,
			Very High

Figure 13: The NASA-TLX workload index to record subjective responses.

6.3. Example Classifications

During the user study, participants were asked to accept or reject potential errors and their corrections — some more difficult than others. Figure 14 shows a selection of potential errors and their corrections.

6.4. Subjective Responses

After the experiment, we acquired subjective responses using the NASA-TLX task load index (Figure 13). We performed ANOVA to test for statistical significance [7]. Mental, physical, and temporal demands were reported slightly higher for participants using focused proofreading but the analysis did not yield any significance. This is unsurprising as the user interface was the same for both groups.

ID	Sex	Age	Classifier
S38	F	20	FP
S57	F	30	FP
S32	M	38	FP
S34	F	21	FP
S21	F	65	FP
S9	M	33	FP
S45	M	28	FP
S31	M	27	FP
S24	F	21	FP
S6	F	38	FP
S28	М	32	GP
S36	F	19	GP
S35	M	26	GP
S25	Μ	26	GP
S54	F	30	GP
S53	M	29	GP
S52	M	27	GP
S51	М	31	GP
S200	F	37	GP
S 3	F	30	GP

Table 5: The novice participants (N = 20) of the forced choice user experiment. The table shows sex (20 female), age (M = 30) and the randomly assigned classifier (focused proofreading as FP, guided proofreading as GP).



Figure 14: A selection of suggested errors and potential corrections during the forced choice user experiment. The star (*) indicates which choice reduces VI. While all participants were able to correctly choose for patch A, only few were able to correctly choose for patch B and C.

- Mental Demand. Participants using focused proofreading stated a higher mental demand M = 11.5(SD = 2.098) than with guided proofreading M = 8.1(SD = 2.003). This was not statistically significant $(F_{1,18} = 3.2574, p = 0.3695)$.
- **Physical Demand.** While naturally physical demand was rated low, participants using focused proofreading stated it slightly higher M = 5.4 (SD = 2.26) than with guided proofreading M = 2.9 (SD = 1.76). This was not statistically significant ($F_{1,18} = 1.7507, p = 0.5454$).
- Temporal Demand. For temporal demand, participants using focused proofreading M = 8.4 (SD = 1.95) reported almost equal to guided proofreading M = 8.3 (SD = 1.99). This was not statistically significant ($F_{1,18} = 0.0033, p = 0.9987$).
- **Performance.** Here, participants were asked to rate their own performance. All participants rated their performance as pretty well (the lower, the better). For focused proofreading M = 6.8 (SD = 1.97) and for guided proofreading M = 7.8 (SD = 2.04). This was not statistically significant ($F_{1,18} = 0.3091, p = 0.8878$).
- Effort. Participants using focused proofreading stated higher effort M = 13.0 (SD = 2.336) than with guided proofreading M = 10.6 (SD = 2.127). This was not statistically significant ($F_{1,18} = 1.1459, p = 0.6599$).
- Frustration. Participants overall reported low frustration. Reported were M = 5.0 (SD = 1.90) using focused proofreading and M = 5.9 (SD = 185) using guided proofreading. This was not statistically significant ($F_{1,18} = 0.3271, p = 0.8818$).

References

- J. A. Bogovic, G. B. Huang, and V. Jain. Learned versus hand-designed feature representations for 3d agglomeration. *International Conference on Learning Representations (ICLR)*, 2014. 2
- [2] K. He, X. Zhang, S. Ren, and J. Sun. Deep residual learning for image recognition. In *The IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, June 2016. 1
- [3] S. Knowles-Barley, V. Kaynig, T. R. Jones, A. Wilson, J. Morgan, D. Lee, D. Berger, N. Kasthuri, J. W. Lichtman, and H. Pfister. Rhoananet pipeline: Dense automatic neural annotation, 2016. (available on arXiv:1611.06973 [cs.CV]). 2
- [4] J. Nunez-Iglesias, R. Kennedy, S. M. Plaza, A. Chakraborty, and W. T. Katz. Graph-based active learning of agglomeration (gala): a python library to segment 2d and 3d neuroimages. *Frontiers in neuroinformatics*, 8, 2014. 2

- [5] S. M. Plaza. Focused Proofreading to Reconstruct Neural Connectomes from EM Images at Scale, pages 249–258. Springer International Publishing, Cham, 2016. 4
- [6] O. Ronneberger, P.Fischer, and T. Brox. U-net: Convolutional networks for biomedical image segmentation. In *Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, volume 9351 of *LNCS*, pages 234–241. Springer, 2015. (available on arXiv:1505.04597 [cs.CV]). 2
- [7] J. P. Shaffer. Multiple hypothesis testing. *Annual Review of Psychology*, 46(1):561–584, 1995. 3, 6
- [8] B. L. Welch. The generalization of student's' problem when several different population variances are involved. *Biometrika*, 34(1/2):28–35, 1947. 3